

Grenoble, France

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Education

Université Grenoble Alpes [Ensimag - Grenoble INP]

Grenoble, France

MSc. in Computer Graphics, Vision and Robotics [MoSIG program]

2020 - 2021

• Tahtawi Scholarship 2020

Université de Bourgogne [VIBOT program]

Dijon, France

MSc 1. IN COMPUTER VISION AND ROBOTICS

2019 - 2020

• Total Grades: Good 14.7/20 with rank: 7/29

Faculty of Computers and Information Science, Ain-Shams University

Cairo, Egypt

PRE-MASTER [POST-GRADUATE] IN COMPUTER SCIENCE

2017 - 2018

• Total Grades: 3.3/4

Faculty of Computers and Information Science, Ain-Shams University

Cairo, Egypt

BSc. IN COMPUTER SCIENCE

2012 - 2016

• Total Grades: Good 72.5 and Graduation Project: Excellent

Work Experience

Laboratoire Hubert Curien - Université Jean Monnet

Saint-Etienne, France

COMPUTER VISION RESEARCHER

Oct. 2021 - Jan. 2022

- FA4.0 (Failure Analysis 4.0) develop a complete pipeline for failure diagnostic of electronic devices.
- Generate databases of synthetic A scanning electron microscope (SEM) images, with ground truth having a realistic geometry, associated with the experimental contexts of the project.
- · Comparison of the quality of the simulation methods (Monte-Carlo method and Deep Learning based methods).
- · Denoising the scanning electron microscopy images using different filters (NLM, Bilateral, Total variation (TV), BM3D).
- https://drive.google.com/file/d/18PFYFkVipsYe8PayDIvoO_p-rS4A-o6m/view

INRIA [MORPHEO Team] Grenoble, France

COMPUTER VISION RESEARCHER

Feb. 2021 - Aug. 2021

- Study Automated General Movements Assessment by Clustering Motion Words from Infants Motion Sequences.
- Develop system to detect Cerebral Palsy problem earlier in the infant in age 3 -5 months.

Datathon DATACARE-COVID19

Dijon, France

COMPUTER VISION DEVELOPER, [COVID-19 SYSTEM]

Apr. 2020 - Apr. 2020

• The goal of this system is to discover the normal states of the slides to be scanned And the pathological cases, and among the cases, to detect the patients From Covid-19. Using the data available will be one or more pivoting sections Chest x-ray in the lungs, and in this system we work to classify the Chest x-ray which have COVID-19 and segment the position of the disease in the lung and the accuracy to detect and Identify the disease through Chest x-ray. Tools: Python, Medical image, Deep learning, Keras, skikit-learn.

DevisionX

MACHINE LEARNING ENGINEER

Nov. 2018 - July. 2019

Cairo, Egypt

• Worked on project to identify the Egyptian national id from images, The output was to recognize the text in it as Arabic using OCR and Another output is to compare the person holding the ID with the image of the ID using Face Detection. Tools: Python, Deep learning, Keras, skikit-learn.

Hackathon Vodafone-010 Cairo, Egypt

COMPUTER VISION DEVELOPER, [VERIFIED & ANTI-SPOOFING PROJECT]

Dec. 2018 - Dec. 2018

A spoofing attack is an attempt to acquire someone else's privileges or access rights by using a photo, video or a different substitute for an
authorized person's face. Tools: Python, Dlib, OpenCV, Deep learning.

Egyptian Engineering Day (EED) competition

Cairo, Egypt

SOFTWARE ENGINEER, [KINECT-BASED MAP BUILDING FOR ROBOT NAVIGATION]

Sep. 2016 - Sep. 2016

- Building a consistent map of the indoor environment by guiding the robot to move and incrementally builds the map. We proposed a method to convert the Kinect's 3D depth data to a 2D area map. Our method can detect obstacle which is missing in a normal laser scan system.
- Tools: C#, LabVIEW, Microsoft Kinect camera.
- ProjectURL:https://www.youtube.com/watch?v=EarvxhsyT4E.

SEPTEMBER 30, 2022 MAHMOUD ALI · RESUME 1



Programming Python, C#, C++, C, MATLAB, Julia, LaTeX

Development Tools Git, AWS, Docker, ROS, Microsoft Kinect Camera, Raspberry pi

> OS Windows, Linux (Ubuntu) Languages English, Arabic, French A2

Projects

6D object pose estimation

Python, PyTorch

LINEMOD/YCB-V dataset

- Study and test the state of the art in 6D object pose estimation. G2L-net is one of the fastest method (23FPS) and FFB6D in the accuracy (99.7).
- This link has my survey for SOTA of 6D pose estimation: https://mahmoud-ali-fcis.github.io/6D-Object-Pose-Estimation/

Person re-identification using Siamese Network

PyTorch

• Train the network with the Triplet loss function and create Anchor, Positive and Negative image dataset, which will be the inputs of triplet loss function, through which the network will learn feature embedding.

Generate handwritten digits using DCGAN

PyTorch

PvTorch

MNIST dataset

 Generate handwritten digit images by create a generator that will learn to generate images that look real and a discriminator that will learn to tell real images apart from fakes.

Control GAN CelebA dataset

• Implement a GAN controllability method using gradients from a classifier. By training a classifier to recognize a relevant feature, you can use it to change the generator's inputs (z-vectors) to make it generate images with more or less of that feature.

Autonomous driving - Car Detection

Python, Tensorflow

COCO dataset

 Using YOLO, Faster RCNN algorithms for car detection in image and video. It's an object detector that uses features learned by a deep convolution neural network to detect an object.

Objects Instance Segmentation

Python, PyTorch

COCO dataset

· Using Pretrained model Mask-RCNN trained on COCO dataset which contains 85 class to detect and segment objects in the scene.

ROBOTONOMI Python, Keras

· Develop an innovative solution in nursing homes with a system capable of performing a semantic similarity analysis on texts and photographs.

Left Ventricle Segmentation in Heart

Python, Keras

ACDC dataset

· Build a deep learning models [U-net, FCN] that automates left ventricle segmentation with high accuracy. The output of the model is a segmentation mask, a pixel-by-pixel mask that indicates whether each pixel is part of the left ventricle or the background.

Offline City Map [Le Creusot, France]

C++, QT

LINK: HTTPS://BITBUCKET.ORG/JOAKO1991/OFFLINEMAP-PROJECT/SRC/MASTER/

• The goal is to make an offline version of a mix between Trip Advisor (user opinions and places reputations) and Google maps (have a map and a way to go to any place). The constrain is to only do it for Le Creusot City.

Computational Geometry and Digital Signal Processing [DSP] Packages

C#

- Apply different algorithms on Shapes to study the Geometric shape. (Convex hull algorithms, Triangulation algorithms, Voronoi algorithms).
- · Analysis and representation of digital signal in both time and frequency domain, including discrete-time convolution, the z-transform, more about other transforms and the discrete-time Fourier transform, FFT algorithm for computation of the DFT algorithm.

Image Processing and Features Packages

MATLAB, Python

- This package included Histogram equalization, Convolution, HARRIS CORNER, k-means clustering and Morphological Transformations.
- · Comparative Analysis for Features-Detection-Description-and-Matching of SIFT, SURF, AKAZE, ORB, BRIEF and BRISK Algorithms .
- Implemented HOG algorithm from scratch which mainly used to describe the structural shape and appearance of an object in an image.

Honors & Awards

Tahtawi Scholarship, Scholarships are available to Egyptian students to study master degree in France.

Campus France